

Using coupled geo-economic models to explore the interplay between coastal protection, natural processes and economic values in developed shorelines

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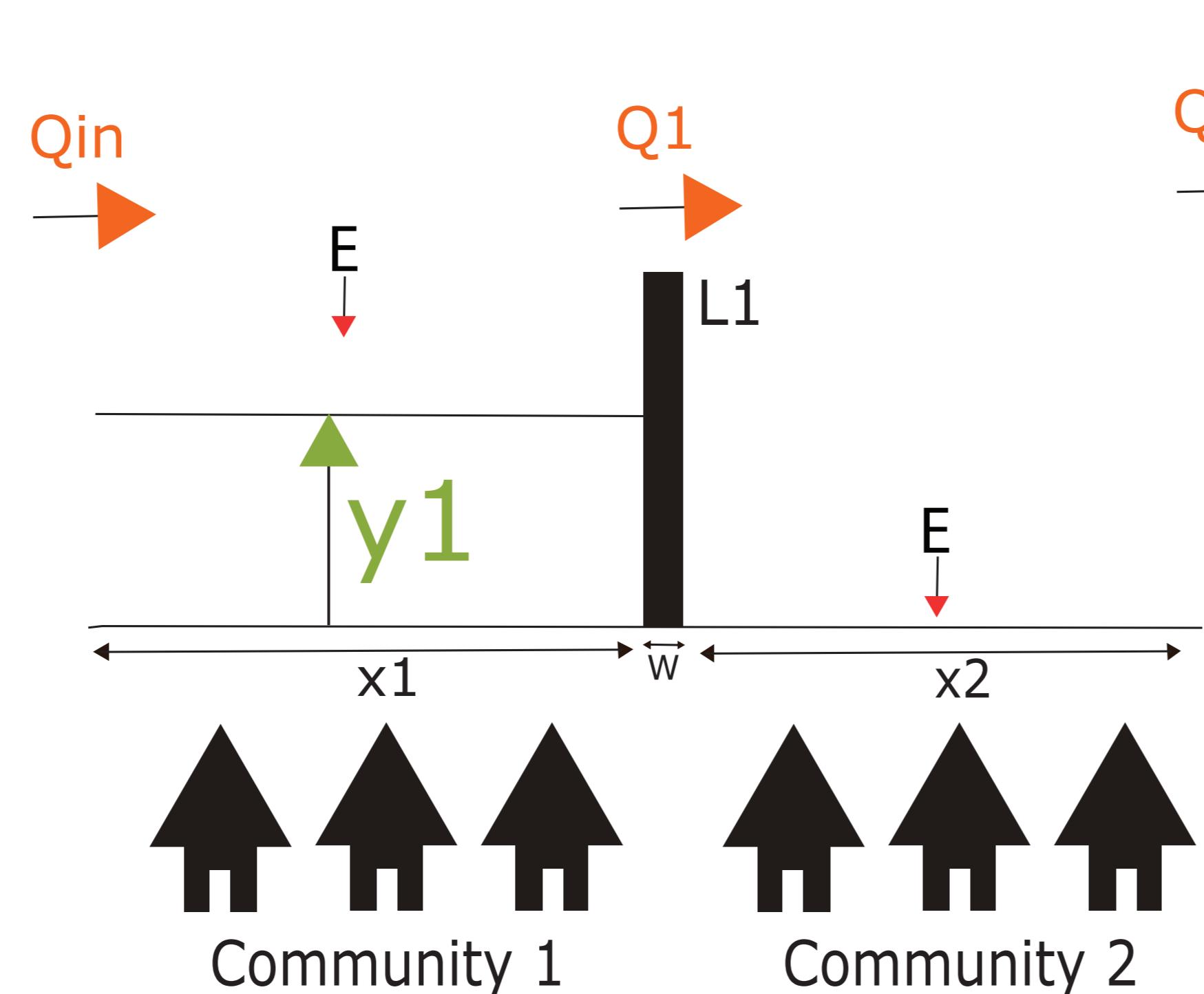
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Effect of groin structures on adjacent communities



$$\max_{L_1} \int_0^{T_{\max}} e^{-\delta t} (B(t) - C(t)) dt$$

Subject to: $\frac{dy_1}{dt} = \frac{Q_{in} - Q_1 - E}{D \cdot x_1}$ Economic Equations

$$B = \alpha \cdot y^{\beta}$$

$$\frac{dy_2}{dt} = \frac{Q_1 - Q_{out} - E}{D \cdot x_2}$$

$$C = \frac{\psi \cdot \gamma \cdot W}{2} L^2$$

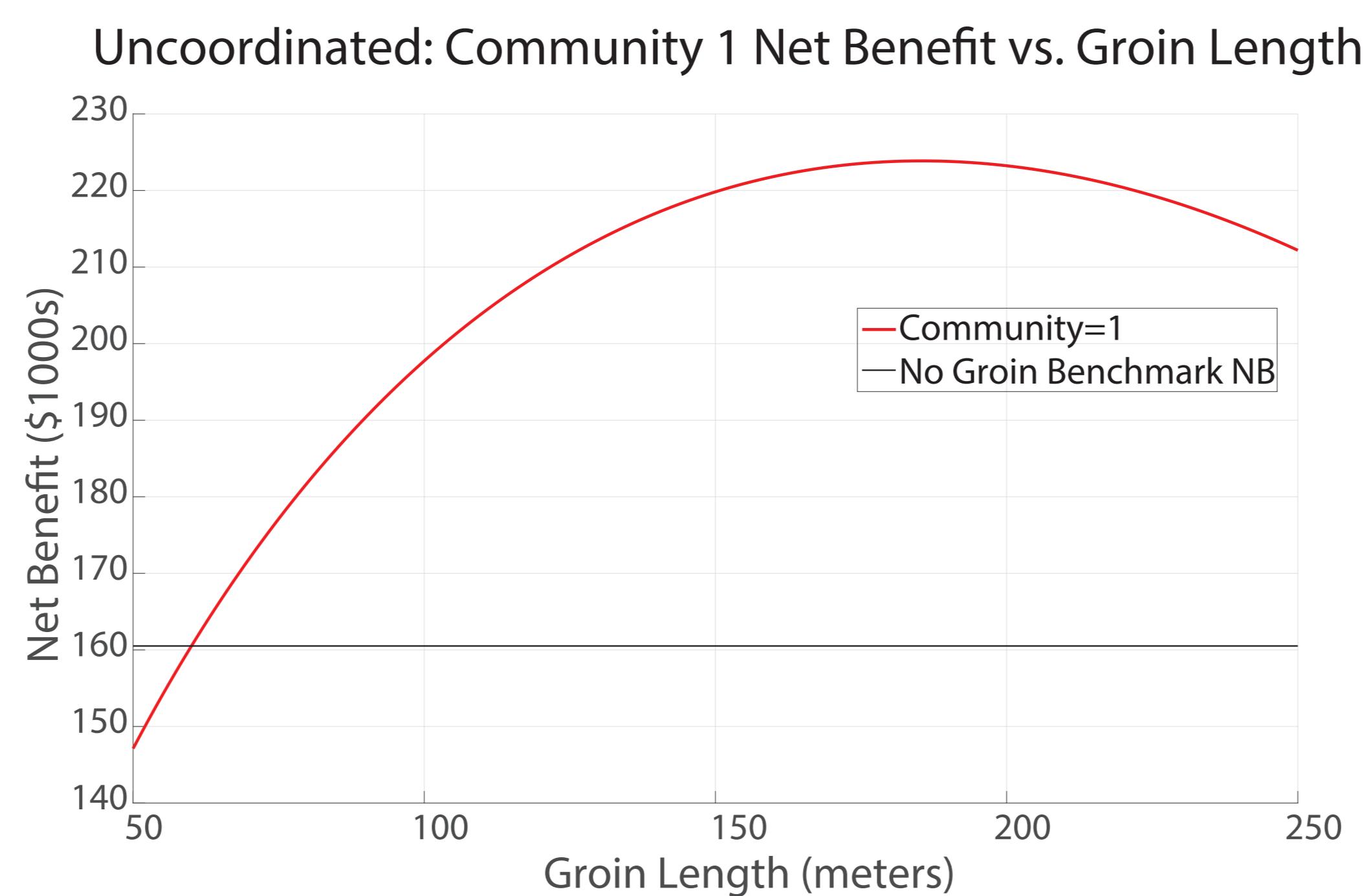
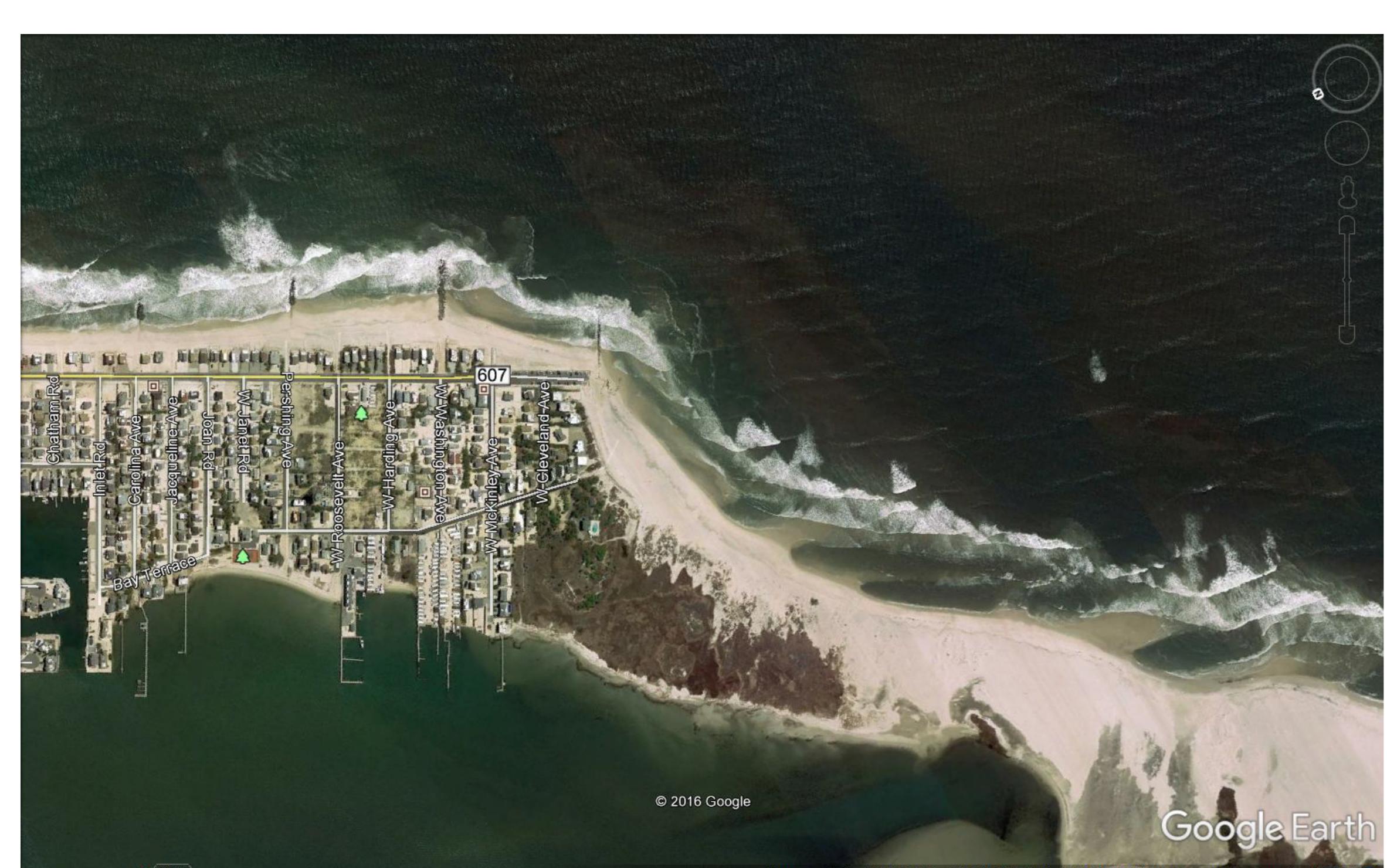


Figure 8. Community 1 net benefits plotted against Community 1 groin length vectors in non-coordination compared to benchmark net benefits for no groin ($\alpha_1=1000$, $\alpha_2=100$).

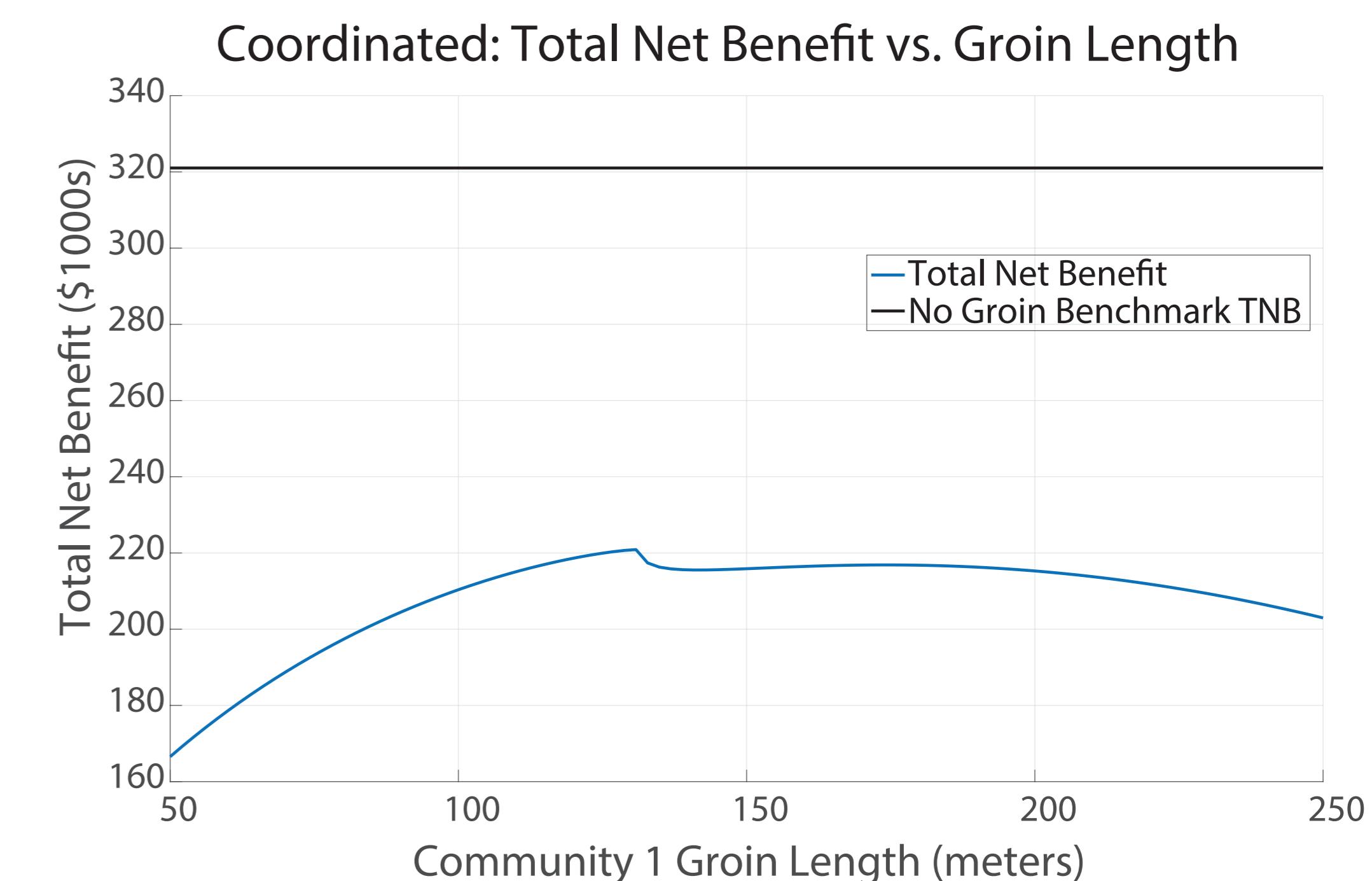
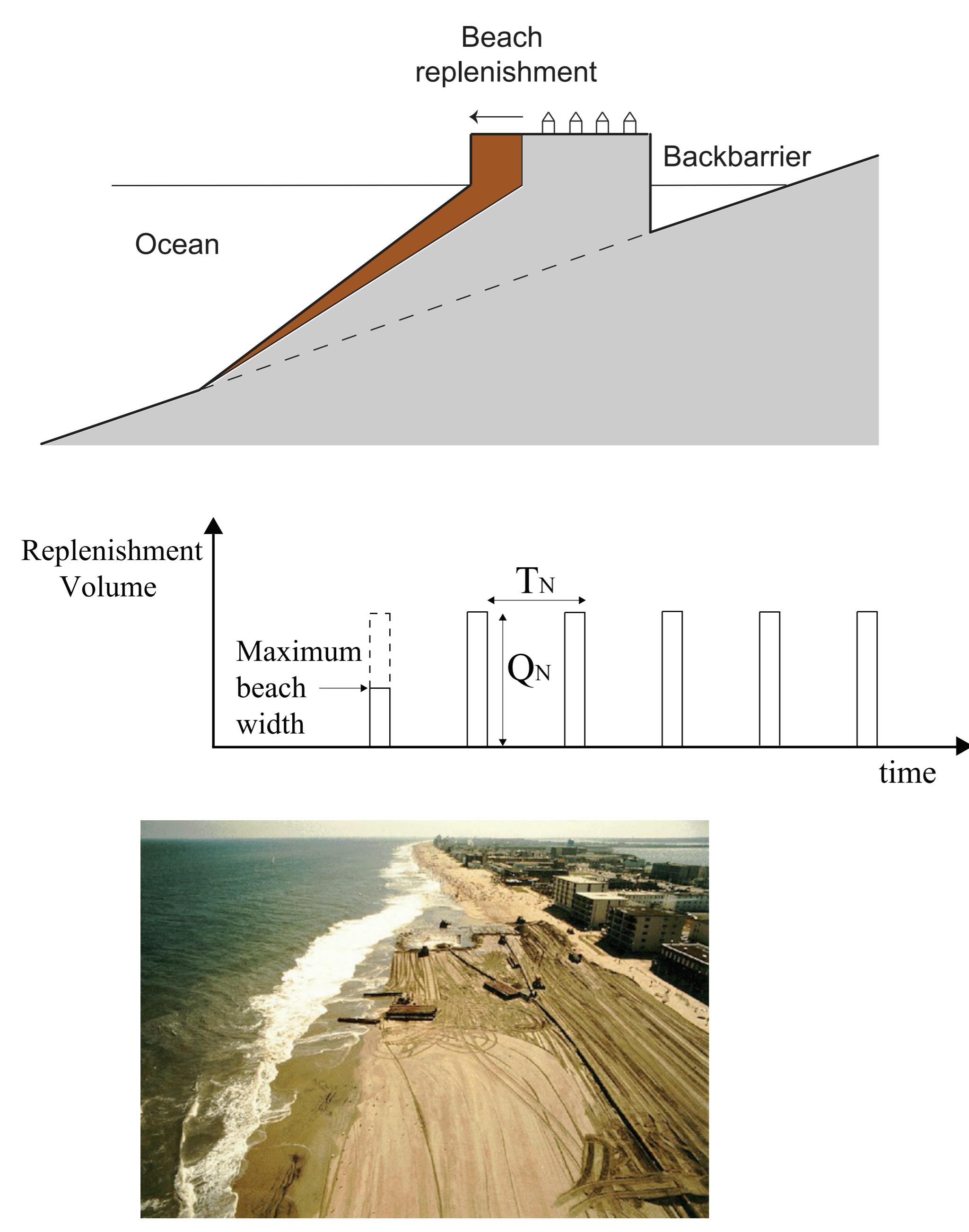


Figure 9. Total net benefits plotted against two communities in coordination compared to benchmark net benefits for no groin. ($\alpha_1=1000$, $\alpha_2=100$).

An integrated model of beach nourishment and cross-shore barrier evolution: beach replenishment or retreat?



$$\max_{T_N, Q_N} \int_0^{T_{\max}} e^{-\delta t} (B(t) - C(t)) dt$$

Subject to:

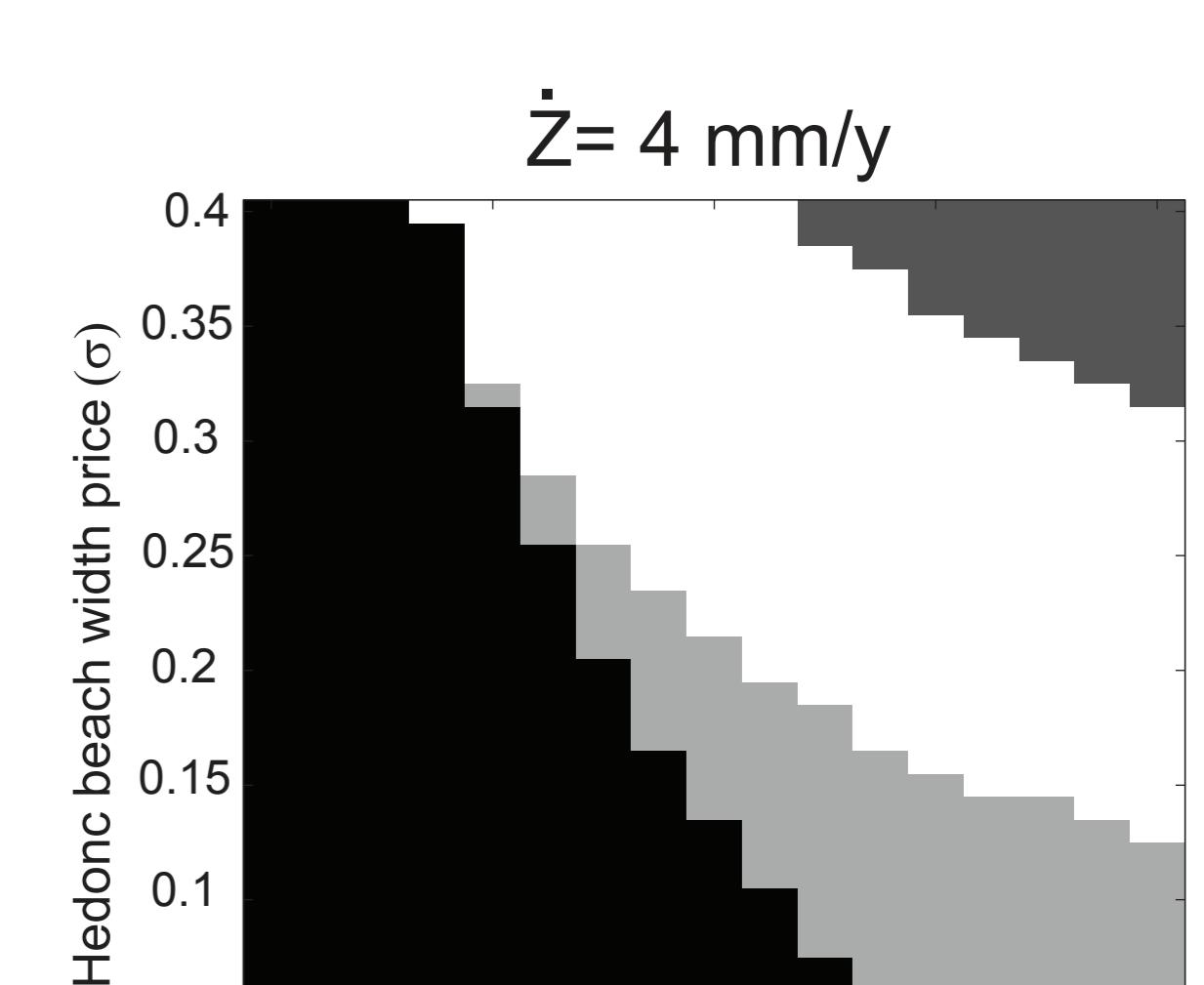
$$\frac{dH}{dt} = \frac{Q_{OW,H} - \dot{z}}{W}$$

$$\frac{dx_S}{dt} = \frac{2Q_{OW}}{2H + D_T} - 4Q_{SF} \frac{H + D_T}{(2H + D_T)^2} - \frac{2v_n(t)}{2H + D_T}$$

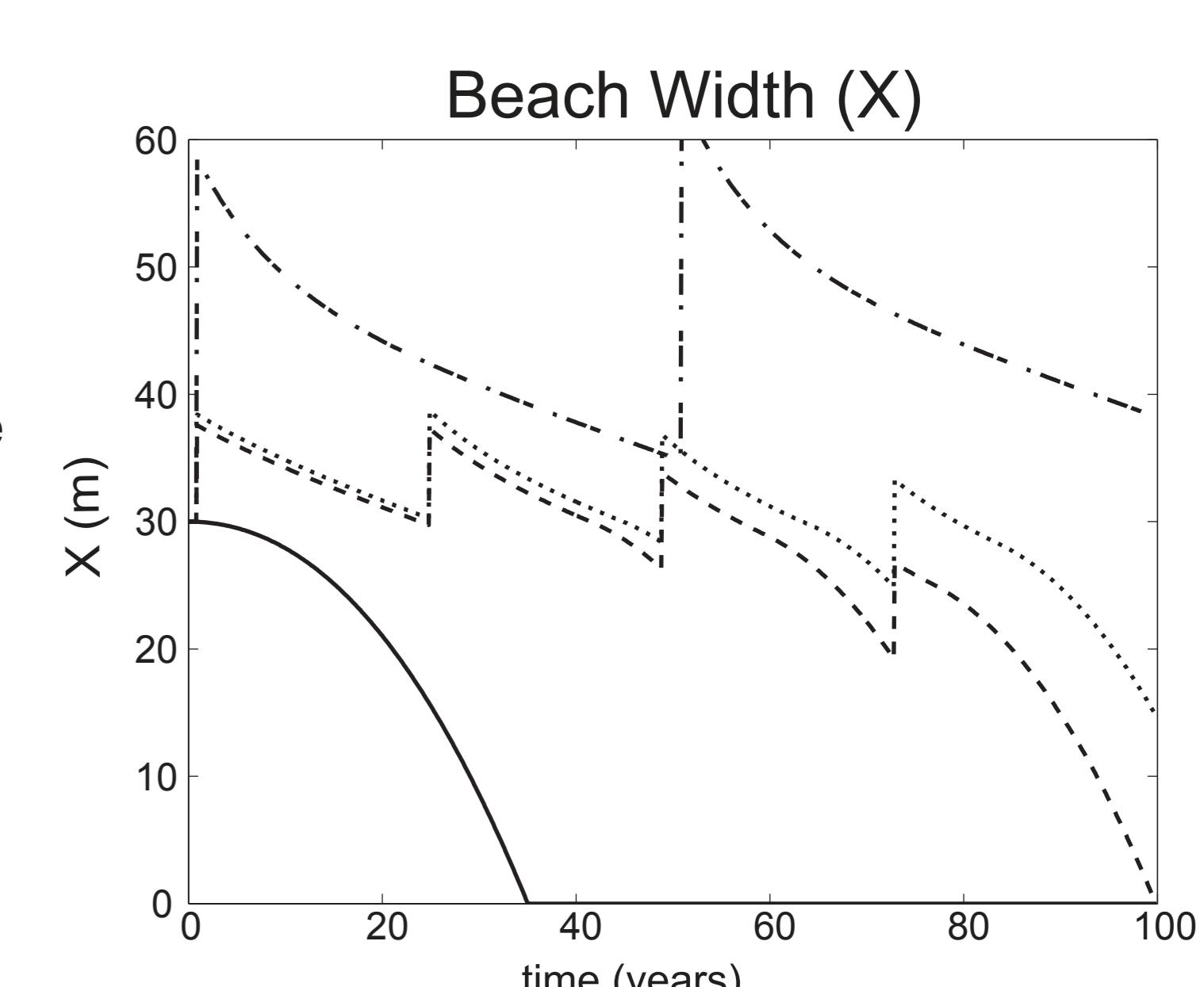
$$\frac{dx_T}{dt} = \frac{4Q_{SF}}{D_T} \frac{H + D_T}{2H + D_T} + \frac{2\dot{z}}{\alpha}$$

$$\frac{dx_B}{dt} = \frac{Q_{OW,B}}{H + D_B}$$

- Nourishment beyond initial shoreline
- Nourishment
- Nourishment & property loss
- No nourishment



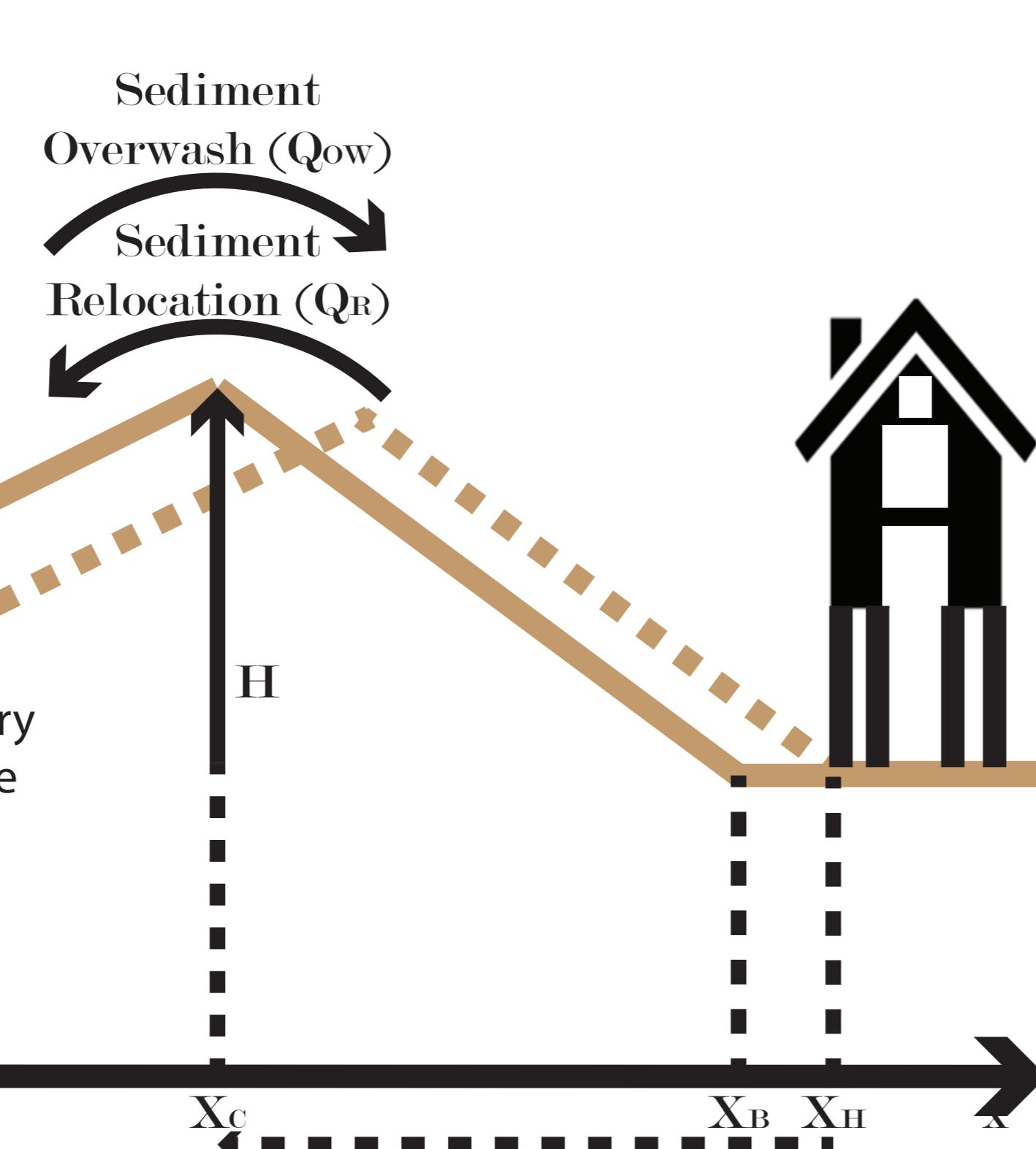
- Nourishment beyond initial shoreline
- Nourishment
- Nourishment & property loss
- No nourishment



A coastal Geo-Economic Model for Artificial Dune Management in New Jersey



$$\max_{Q_N, Q_R} \int_0^{\infty} e^{-\delta t} (B(t) - C(t)) dt$$



Subject to:

$$\frac{dH}{dt} = \frac{Q_N - Q_E - \dot{z}}{p \cdot H}$$

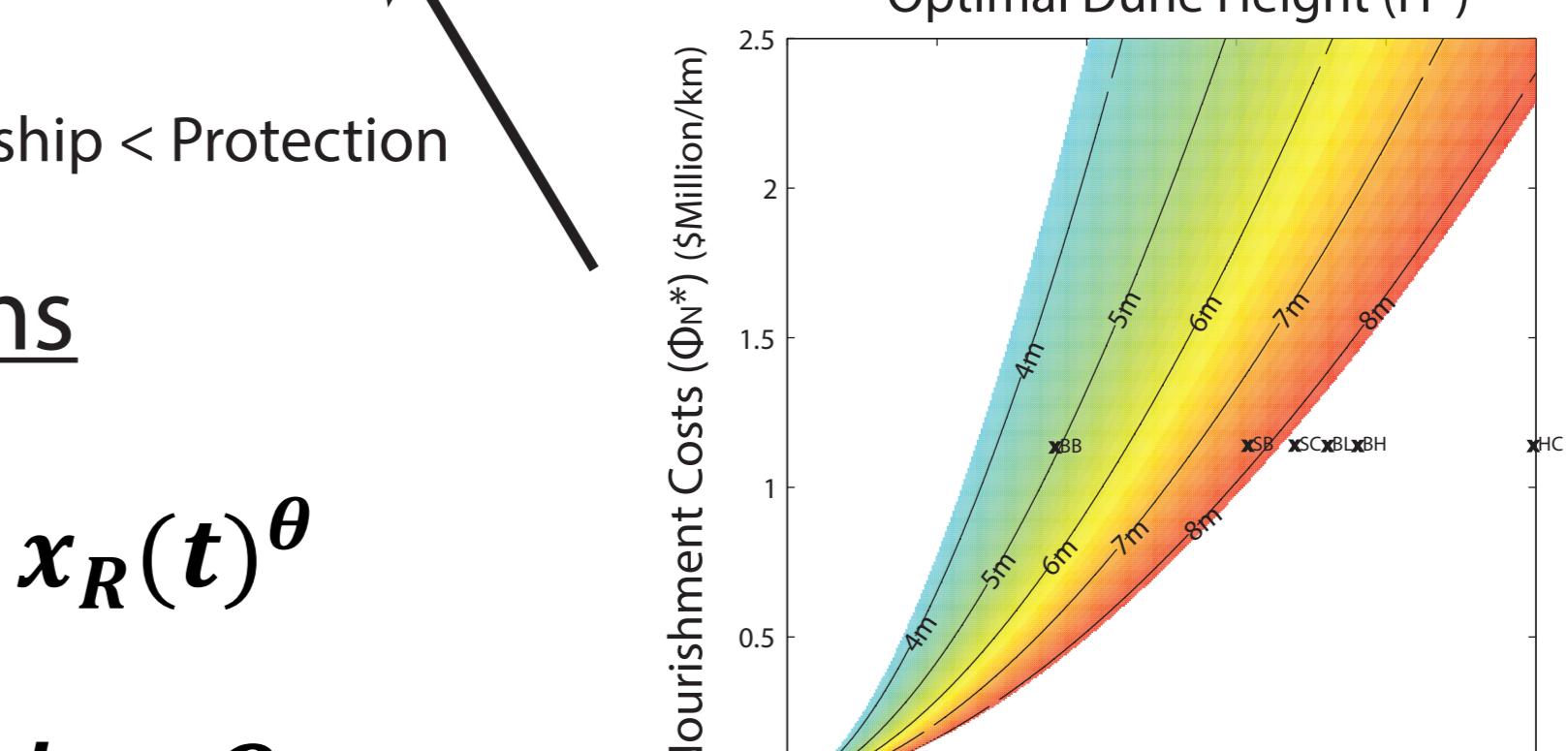
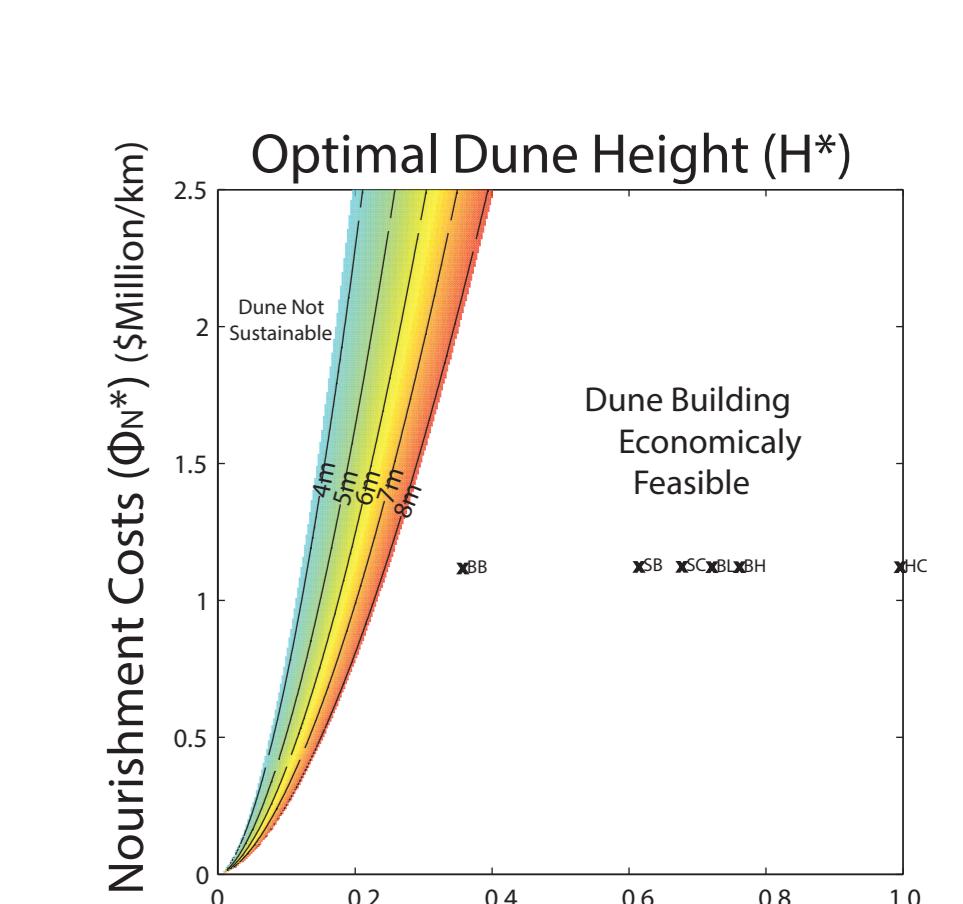
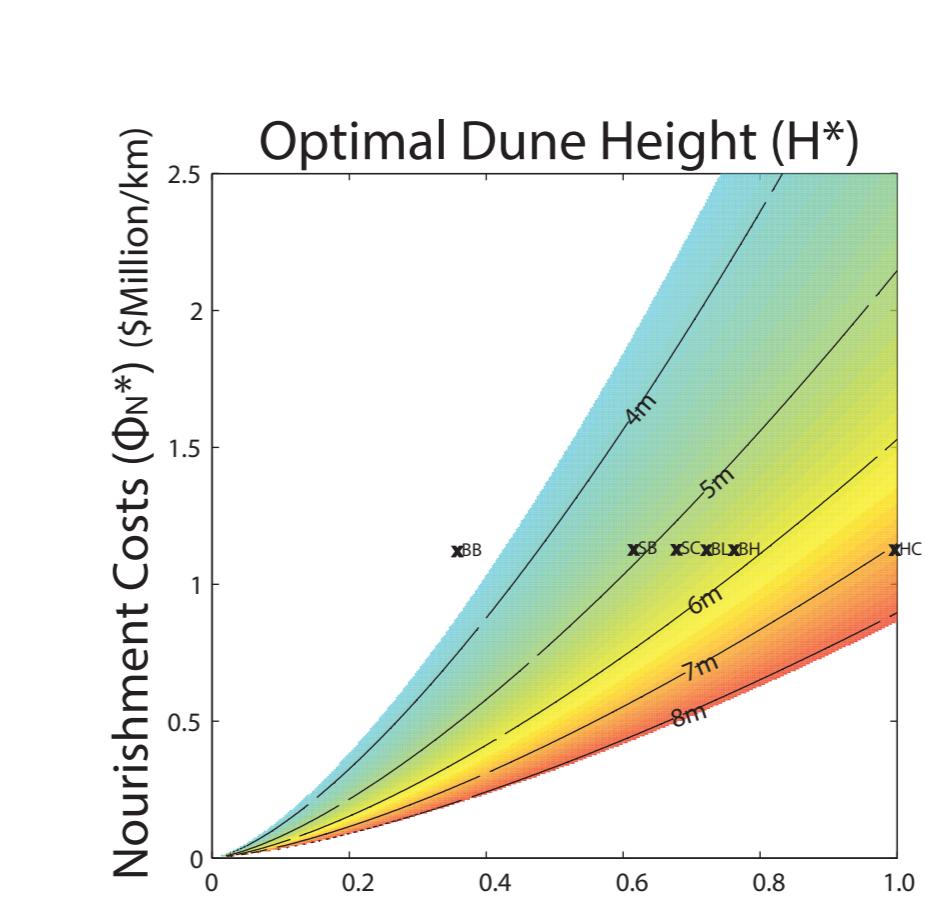
$$\frac{dX_R}{dt} = \frac{Q_R - Q_{ow}}{H}$$

Viewership < Protection

Economic Equations

$$B(t) = \alpha \cdot H(t)^{\beta} \cdot x_R(t)^{\theta}$$

$$C(t) = \phi_N \cdot Q_N + \phi_R \cdot Q_R$$



REFERENCES:

Brad Murray, Dylan McNamara, Gopalakrishnan, S., Smith, M. D., Murray, A. B., etc.