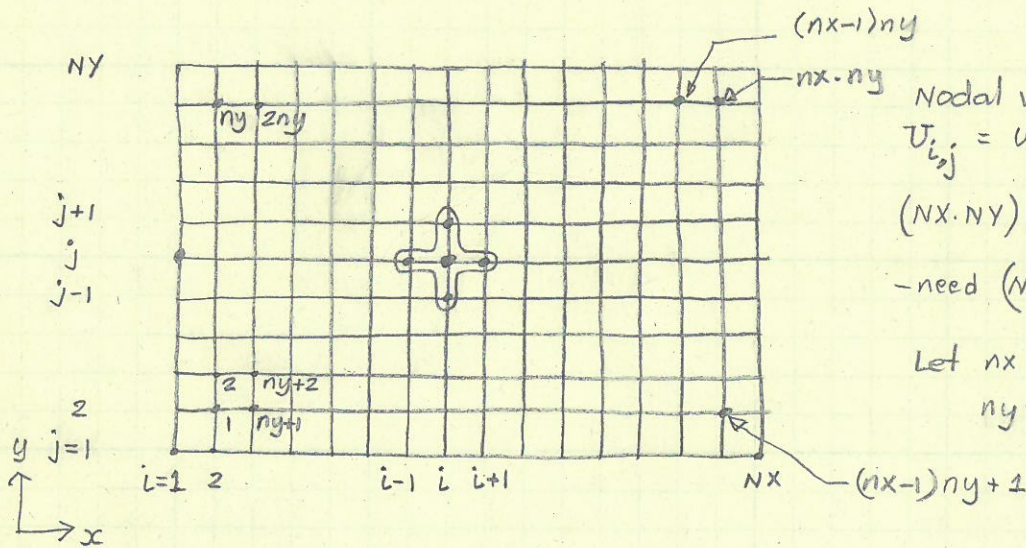


# SOLUTION OF LAPLACE / POISSON EQUATION ON A RECTANGULAR DOMAIN



Nodal values  
 $U_{i,j} = u((i-1)\Delta x, (j-1)\Delta y)$   
 (NX.NY) unknown  $U_{i,j}$ 's  
 - need (NX.NY) equations

Let  $n_x = NX - 2$   
 $n_y = NY - 2$

The Domain is discretized into (NX.NY) grid points. Writing the

finite difference approx. to  $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x,y)$  at  $(x,y) = ((i-1)\Delta x, (j-1)\Delta y)$  or node  $(i,j)$ :

$$(A) \frac{U_{i-1,j} - 2U_{i,j} + U_{i+1,j}}{\Delta x^2} + \frac{U_{i,j-1} - 2U_{i,j} + U_{i,j+1}}{\Delta y^2} = f_{i,j}$$

- writing (A) at each interior nodes generates  $(NX-2)(NY-2)$  equations.
- The additional  $2NX + 2NY - 4$  equations result from B.C. on the 4 edges. One B.C. must be specified at each boundary point. These may be of Type I ( $u$  specified), II ( $\frac{\partial u}{\partial x}$  or  $\frac{\partial u}{\partial y}$  specified) or III ( $\alpha u + \beta \frac{\partial u}{\partial y}$  or  $\beta \frac{\partial u}{\partial x}$  specified) - normal derivatives to the boundary are involved at any boundary point. At least part of the boundary should have type I B.C.

Implementation of B.C. consider boundary point  $(1,j)$  as

an example, with

$$(B) \alpha U_{1,j} + \beta \frac{U_{2,j} - U_{1,j}}{\Delta x} = \gamma$$

$\alpha = 1, \beta = 0$  : TYPE I

$\alpha = 0, \beta \neq 0$  : TYPE II

$\alpha \neq 0, \beta \neq 0$  : TYPE III

$\uparrow \frac{\partial u}{\partial x}$  (normal derivative)

It is customary to assemble a system of equations involving only the interior nodal values of  $U$ . To do this,  $U_{1,j}$  solved from (B) is used in (A) written at  $(2,j)$  (or more generally the B.C. is substituted into the next interior node's (A)).

$$\text{from (B), } U_{1,j} = \frac{(\gamma \Delta x - \beta U_{2,j})}{(\alpha \Delta x - \beta)}$$

$$\text{use in (A) to get: } \frac{U_{3,j}}{\Delta x^2} + \frac{U_{2,j-1} + U_{2,j+1}}{\Delta y^2} + \left( \downarrow + \frac{-\beta}{(\alpha \Delta x - \beta) \Delta x^2} \right) U_{2,j} = f_{i,j} - \frac{\gamma \Delta x}{(\alpha \Delta x - \beta)}$$

$\downarrow$   
 0 for  $\beta=0, \alpha=1$   
 -1 for  $\beta=1, \alpha=0$

(C)

Once  $U_{2,j}$  is obtained from the solution for all interior nodes,  $U_{1,j}$  is obtained from (B).

similar adjustments are needed at the other nodes adjacent to boundary nodes. Note some changes in sign also. e.g.

$$\alpha U_{NX,j} + \beta \frac{U_{NX,j} - U_{NX-1,j}}{\Delta x} = \gamma \text{ etc.}$$

Now, let  $n_x = NX - 2$ ,  $n_y = NY - 2 \rightarrow$  we have  $n_x \cdot n_y$  equations in  $n_x \cdot n_y$  unknowns. Let us number the nodes sequentially, along  $y$ .

$$k = 1, 2, \dots, n_y; n_y + 1, \dots, 2n_y; \dots; (n_x - 1)n_y + 1 \dots, n_x \cdot n_y.$$

The node number for  $(i,j)$  in this scheme would be  $(i-2) \cdot n_y + (j-1)$

The equation at any node number  $k$  involves the  $U$  at nodes  $k-1$  (down),  $k+1$  (up),  $(k-n_y)$  left and  $(k+n_y)$  right; with one missing neighbor on the first and last interior rows/columns.

$\rightarrow$  MATLAB CODE FOR SOLVING IN MATRIX FORM - careful with indexing (first types or no-flux boundaries)

$$\hookrightarrow \text{(C) has } \frac{-2}{\Delta x^2} - \frac{2}{\Delta y^2}, \text{ right side has } f_{i,j} - \frac{U_{1,j}}{\Delta x^2}$$

$\downarrow$  known value

$$\text{no flux: (C) has } \frac{-1}{\Delta x^2} - \frac{2}{\Delta y^2}, \text{ right side has } f_{i,j} (\gamma=0) \text{ OR } f_{i,j} + \frac{\gamma \Delta x}{\alpha \Delta x - \beta}$$



## INTERIOR NODE EQN. AT NODE (2,j)

$$(A) \left(\frac{1}{\Delta x^2}\right) U_{1,j} + \left(\frac{1}{\Delta y^2}\right) U_{2,j-1} + \left(\frac{-2}{\Delta x^2} + \frac{-2}{\Delta y^2}\right) U_{2,j} + \left(\frac{1}{\Delta x^2}\right) U_{3,j} + \left(\frac{1}{\Delta y^2}\right) U_{2,j+1} = f_{2,j}$$

BDRY. CONDITION AT NODE (1,j):

$$\alpha U_{1,j} + \beta \frac{U_{2,j} - U_{1,j}}{\Delta x} = \gamma$$

$$\text{SOLVE FOR } U_{1,j} \text{ IN TERMS OF } U_{2,j} : U_{1,j} = \frac{\gamma \Delta x - \beta U_{2,j}}{(\alpha \Delta x - \beta)}$$

a) TYPE I BDRY. COND.

$$\alpha = 1, \beta = 0, \gamma = \text{GIVEN VALUE OF } U_{1,j}$$

subst. into (A) - eliminate  $U_{1,j}$  as an unknown on the left side by taking it to the right side.

$$\rightarrow \dots + \left(\frac{1}{\Delta y^2}\right) U_{2,j-1} + \left(\frac{-2}{\Delta x^2} + \frac{-2}{\Delta y^2}\right) U_{2,j} + \left(\frac{1}{\Delta x^2}\right) U_{3,j} + \left(\frac{1}{\Delta y^2}\right) U_{2,j+1} = f_{2,j} - \frac{U_{1,j}^{\text{GIVEN}}}{\Delta x^2}$$

MODIFIED FORM OF EQN. (A) AT NODE (2,j) ACCOUNTS FOR TYPE I B.C.

b) TYPE II BDRY. COND.

$$\text{say } \alpha = 0, \beta = 1, \gamma = \text{GIVEN VALUE OF GRADIENT} = \frac{U_{2,j} - U_{1,j}}{\Delta x}$$

subst. into (A) - eliminate  $\frac{-U_{1,j} + U_{2,j}}{\Delta x^2} = \frac{-\gamma}{\Delta x}$  from left side and take to right side.

$$\rightarrow \dots + \left(\frac{1}{\Delta y^2}\right) U_{2,j-1} + \left(\frac{-1}{\Delta x^2} + \frac{-2}{\Delta y^2}\right) U_{2,j} + \left(\frac{1}{\Delta x^2}\right) U_{3,j} + \left(\frac{1}{\Delta y^2}\right) U_{2,j+1} = f_{2,j} + \frac{\gamma}{\Delta x}$$

MODIFIED FORM OF EQN. (A) AT NODE (2,j) ACCOUNTS FOR TYPE II B.C.

SIMILAR ADJUSTMENTS AT NODES  $(N_x-1, j)$  - RIGHT EDGE  $\rightarrow$  NOTE TYPE II B.C.

$(i, 2)$  - BOTTOM EDGE,  $(i, N_y-1)$  - TOP EDGE.

↓

(SEE TABLE FOR HOW EQN. (A) IS MODIFIED FOR EACH OF THESE CASES)

$$\text{WOULD BE } \frac{U_{N_x, j} - U_{N_x-1, j}}{\Delta x} = \gamma$$

$$\text{SO } \frac{U_{N_x, j} - U_{N_x-1, j}}{\Delta x} = \frac{+\gamma}{\Delta x}$$

Becomes  $\frac{-\gamma}{\Delta x}$  when taken to right side

SUMMARY OF MATRIX COEFFICIENTS FOR TYPE I & TYPE II B.C.

"MIDDLE-INTERIOR" NODE (STANDARD CASE)

$$\left(\frac{1}{\Delta x^2}\right) U_{i-1,j} + \left(\frac{1}{\Delta y^2}\right) U_{i,j-1} + \left(\frac{-2}{\Delta x^2} + \frac{-2}{\Delta y^2}\right) U_{i,j} + \left(\frac{1}{\Delta x^2}\right) U_{i+1,j} + \left(\frac{1}{\Delta y^2}\right) U_{i,j+1} = f_{i,j}$$

LEFT EDGE (i=2) INTERIOR NODES

TYPE I

NO TERM

$$f_{i,j} - \frac{U_{1,j}}{\Delta x^2}$$

II

''

$$\left(\frac{-1}{\Delta x^2} + \frac{-2}{\Delta y^2}\right)$$

$$f_{i,j} + \frac{\gamma}{\Delta x^2}$$

RIGHT EDGE (i=Nx-1) INTERIOR NODES

NO TERM

$$f_{i,j} - \frac{U_{N_x,j}}{\Delta x^2}$$

I

II

$$\left(\frac{-1}{\Delta x^2} + \frac{-2}{\Delta y^2}\right)$$

''

$$f_{i,j} - \frac{\gamma}{\Delta x^2}$$

BOTTOM EDGE (j=2) INTERIOR NODES

NO TERM

$$f_{i,j} - \frac{U_{i,1}}{\Delta y^2}$$

I

II

''

$$\left(\frac{-2}{\Delta x^2} + \frac{-1}{\Delta y^2}\right)$$

$$f_{i,j} + \frac{\gamma}{\Delta y^2}$$

TOP EDGE (j=Ny-1) INTERIOR NODES

NO TERM

$$f_{i,j} - \frac{U_{i,N_y}}{\Delta y^2}$$

I

II

$$\left(\frac{-2}{\Delta x^2} + \frac{-1}{\Delta y^2}\right)$$

NO TERM

$$f_{i,j} - \frac{\gamma}{\Delta y^2}$$

NOTE: • FOR 4 CORNER INTERIOR NODES, NEED 2 ADJUSTMENTS EACH, ONLY 3 TERMS IN MATRIX ROW

• PROBABLY BETTER TO USE SUBSCRIPTS ON  $\gamma$  ALSO FOR VARIABLE FLUXES. WHEN  $\gamma=0$  (NO FLUX BDRY.) RIGHT-HAND SIDE DOES NOT CHANGE.

• DONT FORGET  $N_x = n_x + 2$ ,  $N_y = n_y + 2$  ( $N_x, N_y$  refer to the real edges of the rectangles)

• FOR INSULATED/NO-FLUX BOUNDARIES,  $\alpha=0$ ,  $\beta=1$ ,  $\gamma=0 \rightarrow$  no change in RHS.

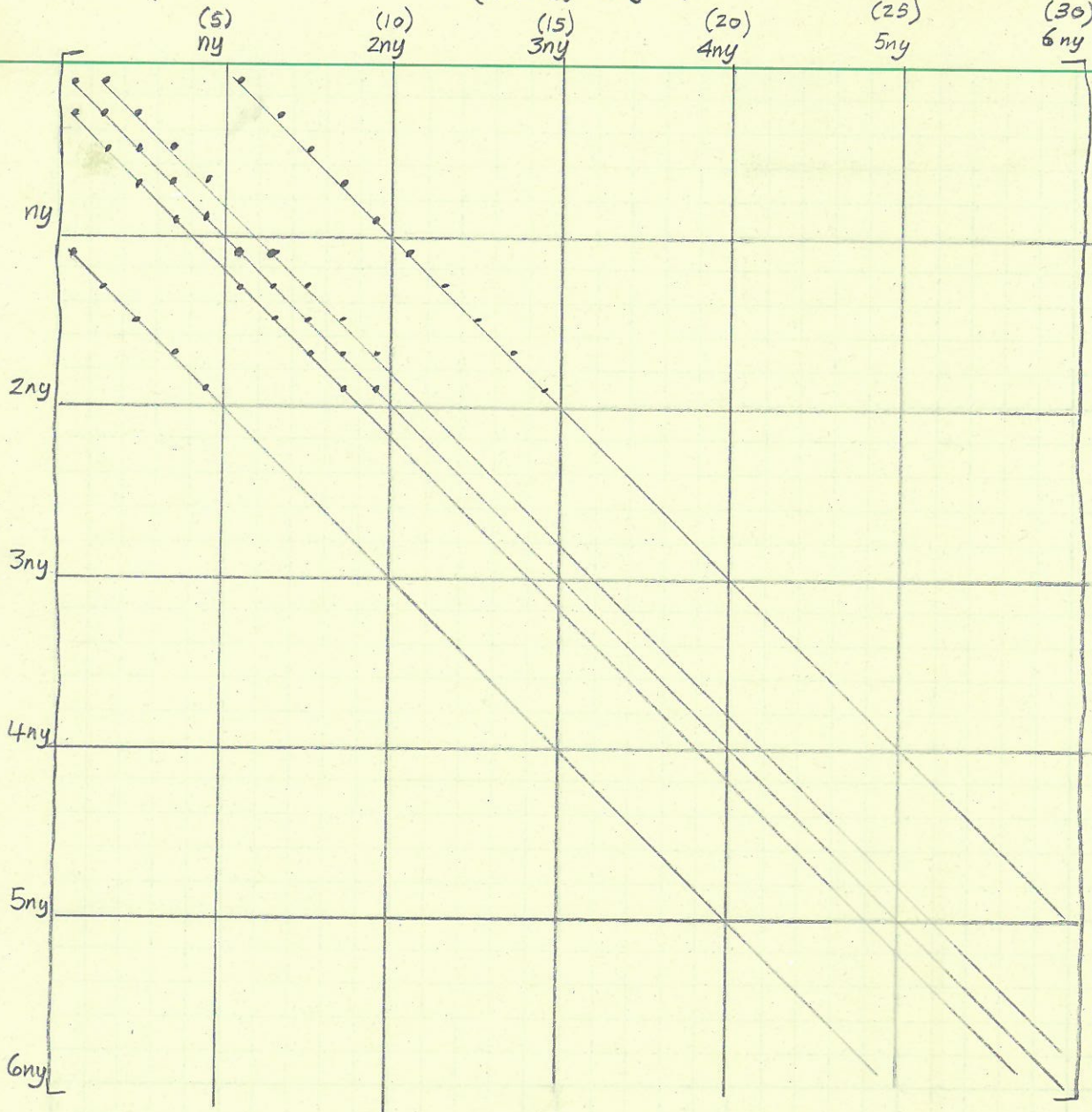
22-141 50 SHEETS  
22-142 100 SHEETS  
22-144 200 SHEETS





22-141 50 SHEETS  
 22-142 100 SHEETS  
 22-144 200 SHEETS

$(nx=6) (ny=5)$



$U_1$   
 $U_2$   
  
 $U_5$   
 $U_6$   
  
 $U_{10}$   
 $U_{11}$   
  
  
  
  
 $U_{29}$   
 $U_{30}$

$f'_1$   
 $f'_2$   
 $\vdots$   
 $\vdots$   
 $f'_{30}$

$f' = f$  adjusted for B.C.

5-banded matrix, block tridiagonal, SYMMETRIC, NEGATIVE DEFINITE,  
 DIAGONALLY DOMINANT (Diagonal element  $\geq$  sum of off-diagonal elements in each row)

```

%this script generates the SPARSE MATRIX needed for
%a matrix-based solution of Laplace equation USING spdiags
%and solves the system of equations
%the grid dimensions are (nx+2)*(ny+2),
%so that the number of interior nodes is nx*ny (more convenient notation)
%the boundary conditions are constant values on the left and right edges,
%with no flux boundaries along the top and bottom edges
%NOTE THAT THE TOTAL NUMBER OF UNKNOWNNS IS n=nx*ny, so A is an nxn matrix
%
nx=101;
ny=101;
n=nx*ny;%total number of unknowns
%set first type boundary values on left and right boundary
uleft=zeros(ny,1);
uright=ones(ny,1);
%delx and dely calculated
delx=1/(nx+1);
dely=1/(ny+1);
%put -4 on the main diagonal
vecmain=-2*ones(n,1)/delx^2+-2*ones(n,1)/dely^2;
%put 1 on the first lower diagonal, later modify it
vecdown=ones(n-1,1)/dely^2;
%put 1 on the first upper diagonal, later modify it
vecup=ones(n-1,1)/dely^2;
%put 1 on the far lower diagonal, later modify it
vecleft=ones(n-ny,1)/delx^2;
%put 1 on the far upper diagonal, later modify it
vecright=ones(n-ny,1)/delx^2;
%set up right-hand side vector as zeros, later modify it
rhs=zeros(n,1);
rhs(fix(nx*ny/2))=10000;
%now modify the vectors that define the matrix for nodes adjacent to
boundaries
%left and right boundaries (no change in vectors, only in rhs
for k=1:ny
    rhs(k)=rhs(k)-uleft(k)/delx^2;
    rhs((nx-1)*ny+k)=rhs((nx-1)*ny+k)-uright(k)/delx^2;
end
%for bottom and top boundaries (no flux, so delete -1/dely^2 from main
%diagonal, and zero out vecup for top boundary, vecdown for bottom boundary
for l=0:nx-1
    %bottom boundary - ibot is node number, ibot-1 is the index in the
    %vector vecdown (one less than ibot)
    ibot=l*ny+1;
    if (ibot ~= 1)
        vecdown(ibot-1)=0;
    end
end

```

```

    end
    vecmain(ibot)=vecmain(ibot)+1/dely^2;
    %top boundary - itop is the node number, the index in vectop is same
    itop=ibot+ny-1;
    if (itop ~= nx*ny)
        vecup(itop)=0;
    end
    vecmain(itop)=vecmain(itop)+1/dely^2;
end
%create sparse matrix S using the spdiags command in MATLAB
%spdiags works a bit non-intuitively. It takes the upper part of
%sub-diagonals and lower part of super-diagonals.
v1=[vecleft;zeros(ny,1)];
v2=[vecdown;0];
v3=vecmain;
v4=[0;vecup];
v5=[zeros(ny,1);vecright];
S=spdiags([v1,v2,v3,v4,v5],[-ny,-1,0,1,ny],n,n);
disp 'sparse matrix'
tic;u=S\rhs;toc
%now construct the uplot vector for contour plotting
uplot=zeros(nx+2,ny+2);
uplot(1,1)=0.0;
uplot(1,2:ny+1)=uleft';
uplot(1,ny+2)=0.0;
for i=1:nx
    for j=1:ny
        index=(i-1)*ny+j;
        iplot=i+1;
        jplot=j+1;
        [index iplot jplot];
        uplot(iplot,jplot)=u(index);
    end
end
for i=2:nx+1
    uplot(i,1)=uplot(i,2);
    uplot(i,ny+2)=uplot(i,ny+1);
end
uplot(nx+2,1)=1.0;
uplot(nx+2,2:ny+1)=uright';
uplot(nx+2,ny+2)=1.0;
x=0:delx:1;
y=0:dely:1;
contourf(x,y,uplot)

```

BASIC ITERATIVE (INDIRECT) METHODS FOR SOLVING  $[A] \underline{u} = \underline{r}$   
 $n \times n$   $n \times 1$   $n \times 1$

$$A_{11} u_1 + A_{12} u_2 + \dots + A_{1n} u_n = r_1$$

$$A_{21} u_1 + A_{22} u_2 + \dots + A_{2n} u_n = r_2$$

⋮

$$A_{n1} u_1 + A_{n2} u_2 + \dots + A_{nn} u_n = r_n$$

STARTING FROM INITIAL GUESS  $\underline{u}^0$ , ITERATIVELY REFINE TO FIND  $\underline{u}$

I. JACOBI ITERATION:

"new"  $u_1^{(m+1)} = (r_1 - A_{12} u_2^{(m)} - A_{13} u_3^{(m)} - \dots - A_{1n} u_n^{(m)}) / A_{11}$

$u_2^{(m+1)} = (r_2 - A_{21} u_1^{(m)} - A_{23} u_3^{(m)} - \dots - A_{2n} u_n^{(m)}) / A_{22}$

etc.

$$u_k^{(m+1)} = (r_k - \sum_{\substack{l=1 \\ l \neq k}}^n A_{kl} u_l^{(m)}) / A_{kk}$$

for  $k=1$  to  $n$  in each iteration

convergence criterion: Let  $\underline{e}^{(m+1)} = [A] \underline{u}^{(m+1)} - \underline{r}$ ,  $e_k^{(m+1)} = \sum_{l=1}^n A_{kl} u_l^{(m+1)} - r_k$

i)  $\max(|e^{(m+1)}|) \leq \text{tolerance}$  or ii)  $\frac{1}{n} \sum_{k=1}^n (e_k^{(m+1)})^2 \leq \text{tolerance}$ .

Jacobi iteration converges if  $|A_{kk}| \geq \sum_{\substack{l=1 \\ l \neq k}}^n |A_{kl}|$  for all  $k$

with strict  $>$  in at least one  $k$ .

"DIAGONALLY DOMINANT" MATRIX. FINITE-DIFFERENCE APPROX. TO

LAPLACE EQN. SATISFY THIS CONDITION (AT LEAST ONE BDRY. POINT TYPE I)

II. GAUSS-SEIDEL ITERATION: MODIFY JACOBI BY USING "new" estimates

as they become available.  $\downarrow$  this "new" estimate is available already

e.g.  $u_2^{(m+1)} = (r_2 - A_{21} u_1^{(m+1)} - A_{23} u_3^{(m)} - \dots - A_{2n} u_n^{(m)}) / A_{22}$

$$u_k^{(m+1)} = (r_k - \sum_{l=1}^{k-1} A_{kl} u_l^{(m+1)} - \sum_{l=k+1}^n A_{kl} u_l^{(m)}) / A_{kk}$$

FOR FULL MATRICES,  $O(n^2)$  OPERATIONS PER ITERATION, BUT FOR SPARSE MATRICES,  $O(\alpha n)$  OPERATIONS PER ITERATION ... COULD BE VERY EFFICIENT

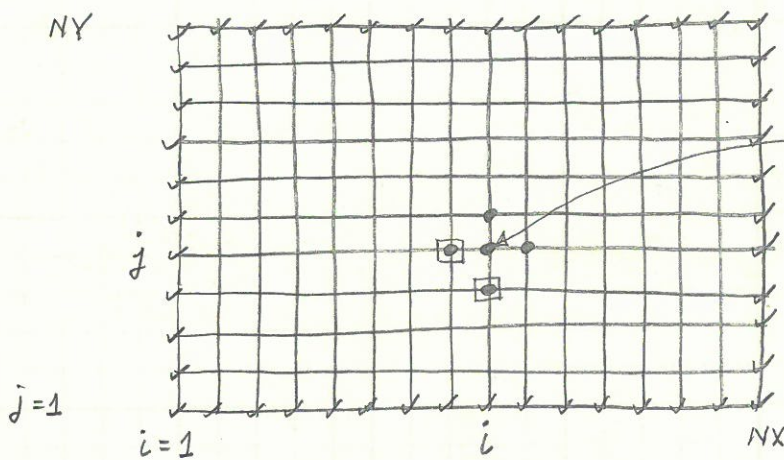
# OF NON-ZERO DIAGONALS





# GRID-BASED ITERATIVE METHODS FOR THE LAPLACE/POISSON EQUATION

• Let us use indexing compatible with MATLAB (no zero indices)



$v =$  KNOWN FROM FIRST TYPE B.C. SAY

"GRID-BASED"  $\Rightarrow$  NOT ASSEMBLING AND STORING A MATRIX.

FINITE DIFF. APPROX. 
$$\frac{U_{i+1,j} - 2U_{i,j} + U_{i-1,j}}{\Delta x^2} + \frac{U_{i,j+1} - 2U_{i,j} + U_{i,j-1}}{\Delta y^2} = f_{i,j}$$

Let  $m =$  ITERATION #,  $m =$  "old",  $m+1 =$  "new" (superscript)

JACOBI: 
$$U_{i,j}^{m+1} = \frac{f_{i,j} - \frac{1}{\Delta x^2} (U_{i+1,j}^m + U_{i-1,j}^m) - \frac{1}{\Delta y^2} (U_{i,j+1}^m + U_{i,j-1}^m)}{(-\frac{2}{\Delta x^2} + \frac{-2}{\Delta y^2})}$$

consider the simple case,  $\Delta x = \Delta y = \Delta$ , Jacobi can be rewritten as:

$$U_{i,j}^{m+1} = U_{i,j}^m + \frac{1}{4} \left( -f_{i,j} \Delta^2 + U_{i-1,j}^m + U_{i,j-1}^m + U_{i,j+1}^m + U_{i+1,j}^m - 4U_{i,j}^m \right)$$

this is the error in the equation at  $(i,j)$  at iteration  $m$ ! can use for convergence check  $\leftarrow \delta_{i,j}^m$

So, 
$$\left\{ \begin{array}{l} \text{for } i = 2 : NX-1 \\ \text{for } j = 2 : NY-1 \\ \quad \text{delta}(i,j) = \\ \quad \text{unew}(i,j) = \\ \text{end} \\ \text{end} \\ \quad d = \max(\max(\text{abs}(\text{delta}))) \\ \quad u = \text{unew} \end{array} \right. \quad \dots \text{ this is basically what we need to do, while } d > \text{toler}$$

IF WE FOLLOW THE JACOBI APPROACH CLOSELY, NOTE THAT WHEN WE GET TO  $(i, j)$ , WE ALREADY HAVE  $U_{i,j-1}^{m+1}$ ,  $U_{i-1,j}^{m+1}$  - WHY NOT USE THESE HOPEFULLY BETTER ESTIMATES?

### GAUSS-SEIDEL:

$$U_{i,j}^{m+1, G-S} = U_{i,j}^m + \frac{1}{4} \left( -f_{i,j} \Delta^2 + \underbrace{U_{i-1,j}^{m+1} + U_{i,j-1}^{m+1} + U_{i+1,j}^m + U_{i,j+1}^m - 4U_{i,j}^m}_{\delta_{i,j}^{m, G-S}} \right)$$

In this case there is no need to distinguish "old" and "new" - can overwrite the old  $u$  values as and when they are updated!

### SUCCESSIVE OVER-RELAXATION: (SOR)

$$U_{i,j}^{m+1, SOR} = U_{i,j}^m + \omega \delta_{i,j}^{m, G-S}, \quad \text{where } \omega > \frac{1}{4} \quad (\omega = \frac{1}{4} \text{ is same as Gauss-Seidel})$$

( $< \frac{1}{4} \Rightarrow$  "under relaxation")

can rewrite as: (note:  $\delta_{i,j}^{m, G-S} = 4(U_{i,j}^{m+1, G-S} - U_{i,j}^m)$ )

$$U_{i,j}^{m+1, SOR} = (1-4\omega) U_{i,j}^m + 4\omega U_{i,j}^{m+1, G-S}$$

for  $\omega < \frac{1}{4}$ , this is like giving some weight to  $U_{i,j}^{m+1}$  (Gauss-Seidel) and some weight to  $U_{i,j}^m$  (old). For  $\omega > \frac{1}{4}$ , we are assigning a negative weight to  $U_{i,j}^m$  and excess weight to  $U_{i,j}^{m+1}$  (Gauss-Seidel)! this turns out to accelerate the convergence!! (works for  $\omega < \frac{1}{2}$ )

IN THE NEXT PROJECT WE WILL SEE HOW VARYING  $\omega$  INFLUENCES THE NUMBER OF ITERATIONS NEEDED FOR CONVERGENCE.

CAN FOR-LOOPS IN JACOBI / GAUSS-SEIDEL / SOR BE REPLACED WITH A SINGLE LINE ACTING ON A WHOLE MATRIX? (VECTORIZING?)

WITH TYPE-II B.C., the nodal equations are changed as we discussed earlier while developing the matrix form.

e.g. with Type II on top edge, the eqns. for the uppermost interior nodes becomes: ( $i, j = NY-1$ )

$$\frac{1}{\Delta x^2} U_{i-1, NY-1} + \frac{1}{\Delta y^2} U_{i, NY-2} + \left( \frac{-2}{\Delta x^2} + \frac{-1}{\Delta y^2} \right) U_{i, NY-1} + \frac{1}{\Delta x^2} U_{i+1, NY-1} = f_{i, NY-1} + \frac{\gamma}{\Delta y}$$

specified flux  $\downarrow$

For  $\Delta x = \Delta y = \Delta$ , JACOBI ITERATION EQN. BECOMES:

$$U_{i, NY-1}^{m+1} = U_{i, NY-1}^m + \frac{1}{3} \left( -f_{i, NY-1} \Delta^2 - \gamma \Delta + U_{i-1, NY-1}^m + U_{i, NY-2}^m + U_{i+1, NY-1}^m - 3 U_{i, NY-1}^m \right)$$

modified  $\delta_{i, NY-1}^m$

$\uparrow$   
 $\frac{1}{3}$ , NOT  $\frac{1}{4}$

SIM.  $U_{i, NY-1}^{m+1, G-S} = U_{i, NY-1}^m + \frac{1}{3} \left( \dots + \delta_{i, NY-1}^{m+1} + \delta_{i, NY-1}^{m+1} + \dots - \dots \right)$

modified  $\delta_{i, NY-1}^{m, G-S}$

FOR SOR,

$$U_{i, NY-1}^{m+1, SOR} = U_{i, NY-1}^m + \frac{4}{3} \omega \delta_{i, NY-1}^{m, G-S}$$

- THESE MODIFICATIONS WILL NEED TO BE USED AT FIRST/LAST ROW/COLUMN INTERIOR NODES ADJACENT TO A TYPE II BOUNDARY NODE. THE CORRESPONDING BOUNDARY NODES  $U_{i, NY}$  (OR EQUIVALENT) ARE NOT INVOLVED IN THE SYSTEM OF EQS. SOLVED. THEY ARE OBTAINED AFTER FULL SOLUTION, E.G.  $U_{i, NY}^{final} = U_{i, NY-1}^{final} + \gamma \Delta y$  ETC.
- AT CORNER NODES, IF YOU HAVE TWO TYPE II BOUNDARIES, THE EQUATION WILL CHANGE FURTHER

